



**Fraunhofer** Institut  
Autonome Intelligente  
Systeme

## **Adaptation of Strategies in a Spatial IPD**

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## **Schedule**

1. Basic interaction: Prisoner's Dilemma
2. Spatial interaction and agent dynamics
3. Spatial games with 3 strategies
4. Spatial games with 8 strategies
5. Conclusions

## Basic Interaction: Prisoner's Dilemma (PD)

- ▶ ultimate goal of agent  $i$ : utility maximization  
depends on action of opponent  $j \Rightarrow$  different strategies
- ▶ PD game: paradigmatic example for interaction of 2 agents
  - choice between:  $C$ : to cooperate,  $D$ : “to defect”  
choose  $C$  or  $D$  without knowing opponent's move

	<b>C</b>	<b>D</b>
payoff matrix:	<b>C</b> $R = 3$	$S = 0$
	<b>D</b> $T = 5$	$P = 1$

- ▶ *dilemma*:  $T > R > P > S \Leftrightarrow 2R > T + S$   
it pays more to defect against cooperators, but global utility is maximized for cooperators

## Important: number of encounters $n_g$

➤  $n_g = 1$ : one-shot 2-person PD:  $\mathcal{D}$  is ESS

➤  $n_g \geq 2$ : *iterated PD*

differences only if memory of  $n_m \geq 1$  steps

➤  $n_m = 1$ : *strategy*  $\Rightarrow$  3-bit binary string  $[I_0|I_cI_d]$

$I_0$  : initial decision (*deterministic game*)

$I_c, I_d$ : code response of agent  $i$  to previous move of agent  $j$

$I_c = 1$ , if  $j$  was  $\mathcal{C}$  before and  $i$  is  $\mathcal{C}$  now

$I_c = 0$ , if  $j$  was  $\mathcal{C}$  before and  $i$  is  $\mathcal{D}$  now

$I_d = 1$ , if  $j$  was  $\mathcal{D}$  before and  $i$  is  $\mathcal{D}$  now

$I_c = 0$ , if  $j$  was  $\mathcal{D}$  before and  $i$  is  $\mathcal{C}$  now

- results in  $s = 8$  different strategies

s	Strategy	Acronym	Bit String
0	suspicious defect	sD	000
1	suspicious anti-Tit-For-Tat	sATFT	001
2	suspicious Tit-For-Tat	sTFT	010
3	suspicious cooperate	sC	011
4	generous defect	gD	100
5	generous anti-Tit-For-Tat	gATFT	101
6	generous Tit-For-Tat	gTFT	110
7	generous cooperate	gC	111

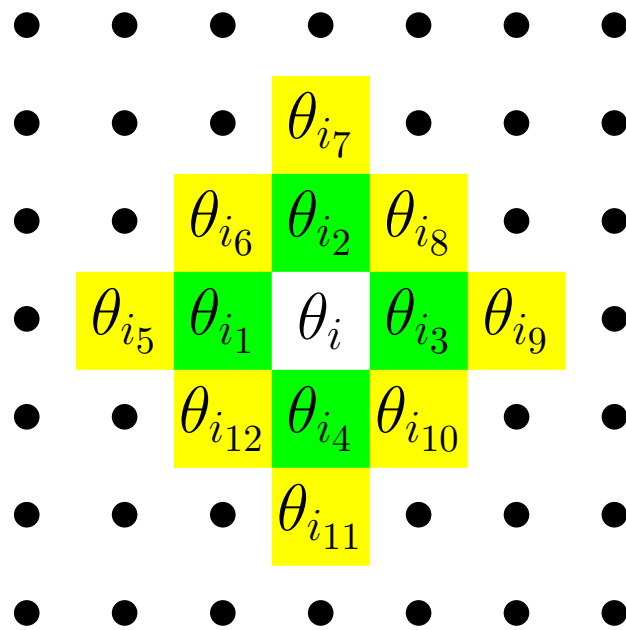
- ▶ suspicious strategies (s=0,1,2,3): initial defection
- generous strategies (s=4,5,6,7): initial cooperation
- rigid strategies (s=0,3,4,7): agents always behave the same

- ▶ known result for 2-person IPD:  
(g)TFT most successful strategy ( $n_g \geq 4$ )
- ▶ **Now:** N agents with heterogeneous strategies and local interaction

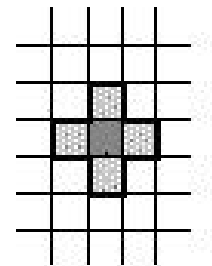
### Questions:

- ▶ meaning of “lunatic” strategies?
- ▶ imitation behavior and  $n_g \leq 4$ : which strategies survive?
- ▶ role of spatial heterogeneity  $\Rightarrow$  local interaction?  
spatial domains of prevailing strategies?
- ▶ non-stationary dynamics?

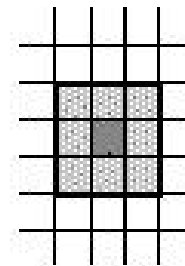
# Spatial Interaction of Agents



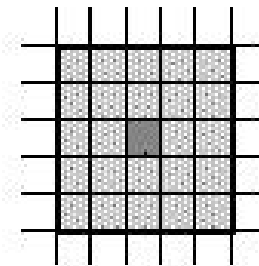
- cell  $i$  with different states  $\theta_i$
- interaction with neighbors  $j$



(a)  
von Neumann  
neighbourhood



(b)  
3x3 Moore  
neighbourhood



(c)  
5x5 Moore  
neighbourhood

*History:* v. Neumann, Ulam (1940s), Conway (1970), Wolfram (1984), ...

*Socio/Economy:* Sakoda (1949/1971), Schelling (1969), Albin (1975), ...

## Agent Dynamics

- ▶ *microscopic description*: agent  $i$  (position:  $r_i$ )
  - internal degree of freedom  $\theta_i \in \{0, 1, \dots, 7\} \Rightarrow$  strategy
- ▶ *local* interaction of agent  $i$  with its 4 nearest neighbors
  - decomposition of *5-person* game into 4 independent, simultaneous *2-person* games, interaction: **2-person IPD**
- ▶ *dynamics*: adopt strategy of most successful agent  
 $j^* = \arg \max_{j=0, \dots, m} a_{ij}$  in neighborhood  $m$   
$$\theta_i(G + 1) = \theta_{i_{j^*}}(G)$$
  - *deterministic game*, time step in generations  $G$



➤ total payoff of agent  $i$

$$a_i(\theta_i) = \sum_{j=1}^{n-1} a_{\theta_i \theta_{ij}} = \sum_s a_{\theta_i s}(n_g) \cdot k_i^s ; \quad k_i^s = \sum_{j=1}^{n-1} \delta_{s \theta_{ij}}$$

- $a_{\theta_i s}(n_g) \Rightarrow 8 \times 8$  payoff matrix dependent on  $n_g$
- assumption: strategy can be observed/deduced

➤ global variables

- frequencies of strategies:  $f_s(G) = \frac{1}{N} \sum_{i=1}^N \delta_{\theta_i s}$
- average payoff per agent  $\bar{a}$ :

$$\bar{a} = \frac{1}{N} \sum_{i=1}^N a_i(\theta_i) = \sum_s f_s(G) \cdot \bar{a}_s ; \quad \bar{a}_s = \frac{\sum_i a_i(\theta_i) \delta_{\theta_i s}}{\sum_i \delta_{\theta_i s}}$$

## Example: Spatial Game with Three Strategies

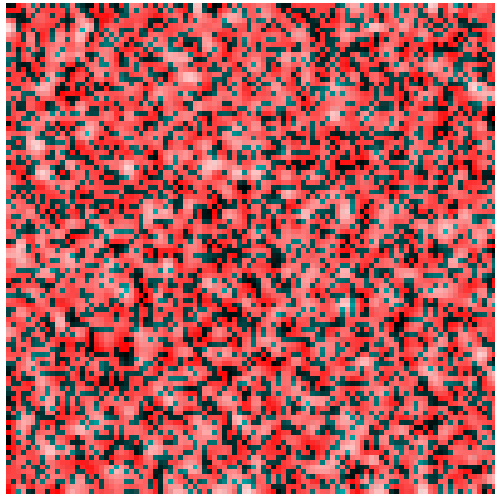
[110]: TFT (“tit for tat”)  $\Rightarrow$  cooperative as long as opponent is cooperative

[000]: always defective

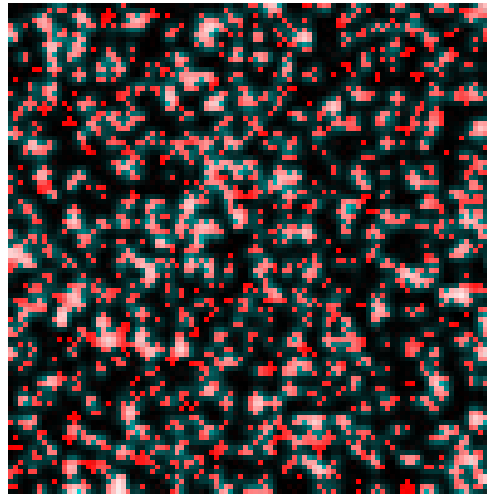
[001]: anti-TFT  $\Rightarrow$  defective to cooperators, cooperative to defectors

➤ random initial distribution,  $f^s(0) = 1/3$ ,  $N = 100 \times 100$

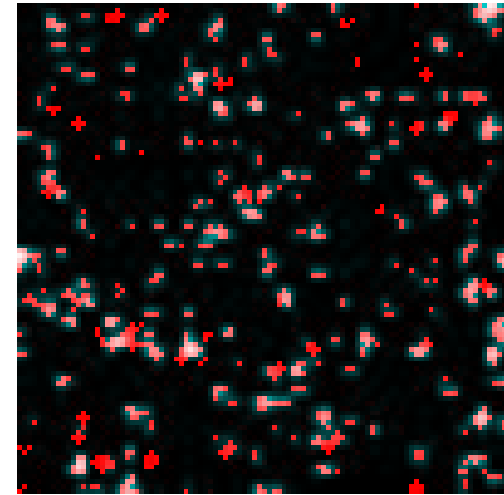
➤ results of computer simulations:  $n_g = 2$   $n_g = 3$



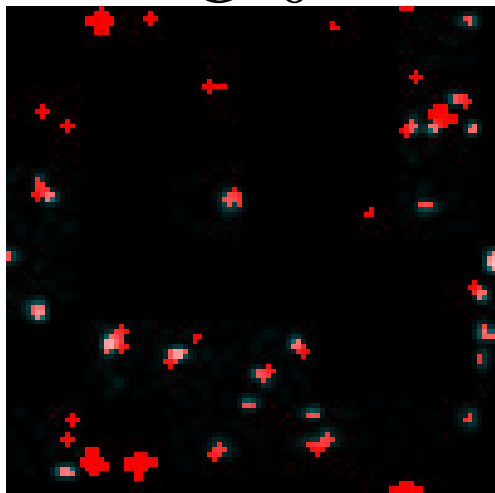
G=0



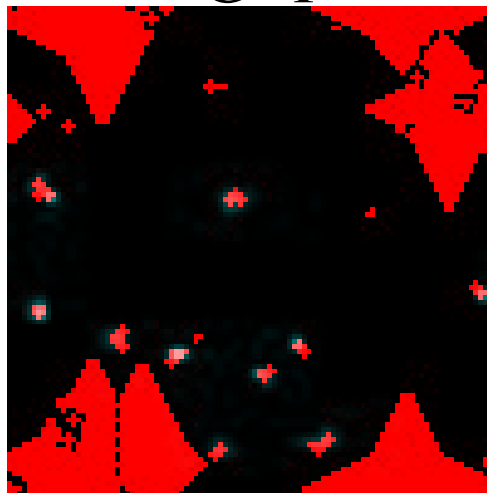
G=1



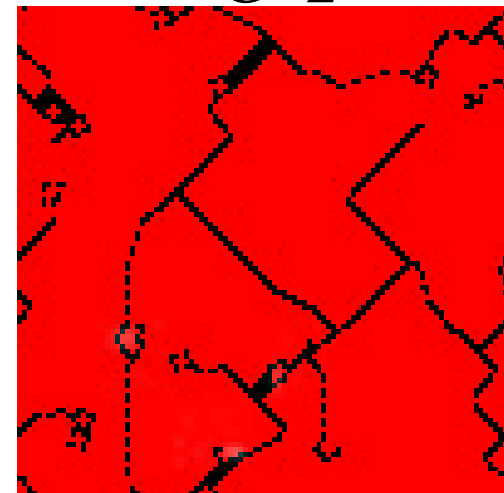
G=2



G=4



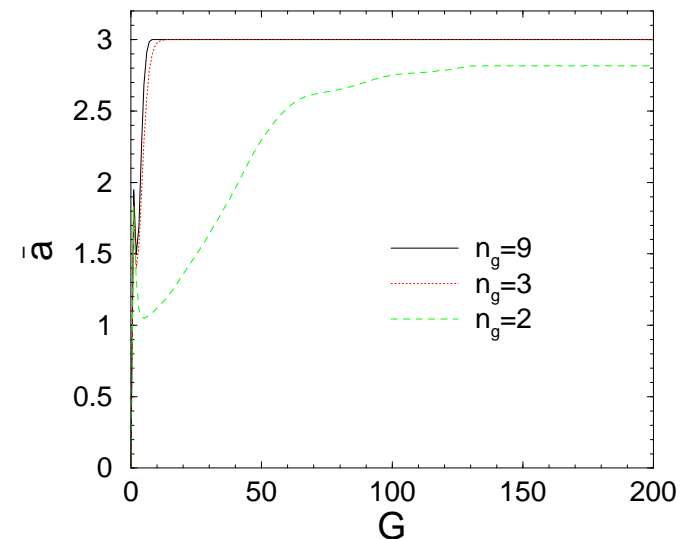
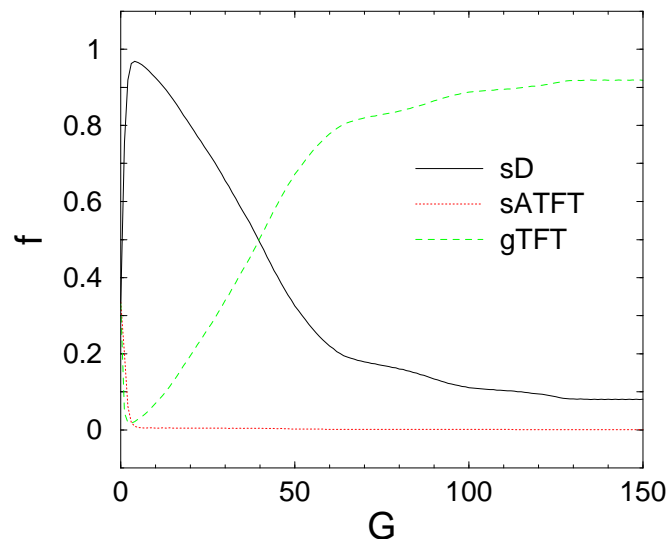
G=22



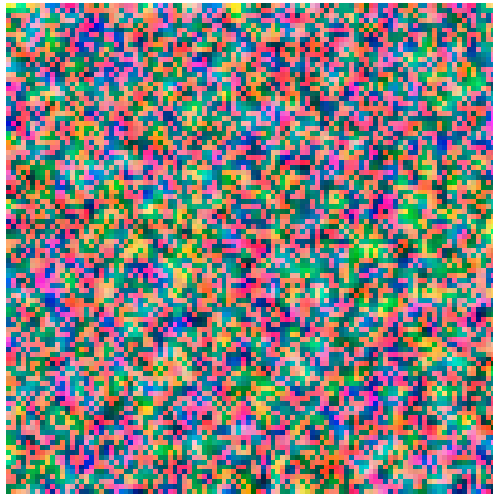
G=150

## Results:

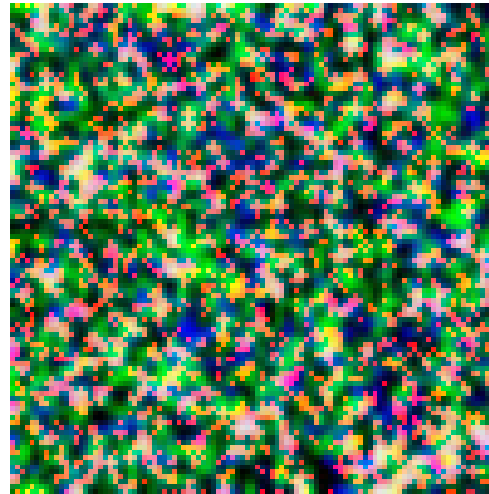
- ▶ *early stage*: steep decline of (partially) cooperative agents ([110], [001])  $\Rightarrow$  survive in small clusters
- ▶ *late stage*: overwhelming rollback of cooperation  $\Rightarrow$  TFT takes over, majority
- reason: defectors have “killed” anti-TFT



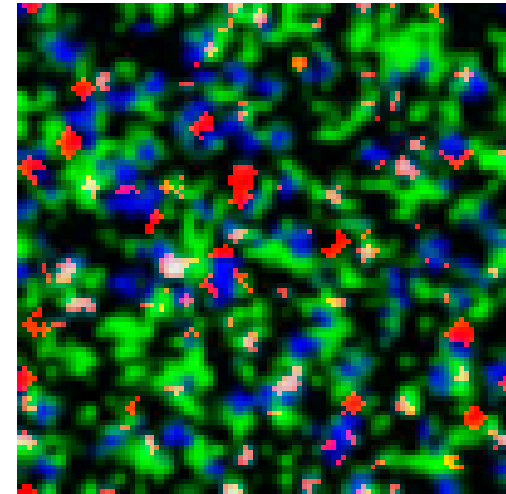




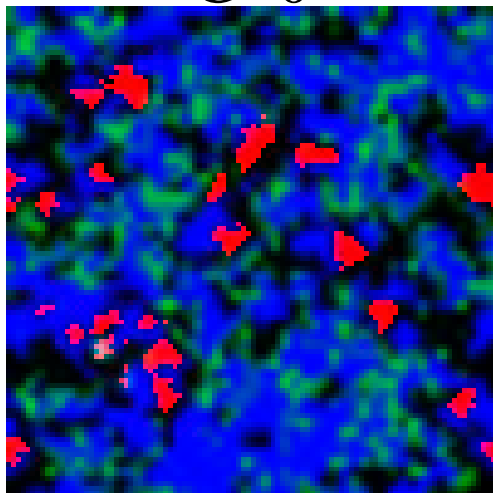
G=0



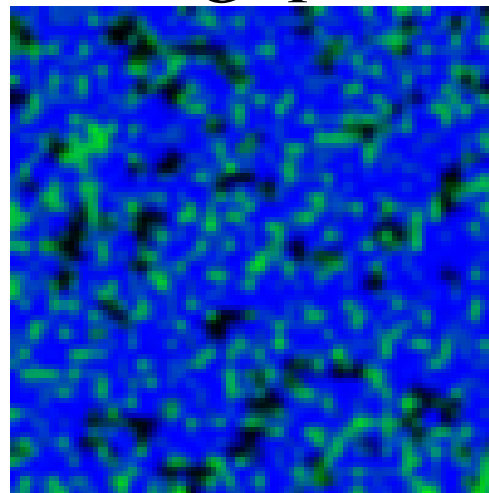
G=1



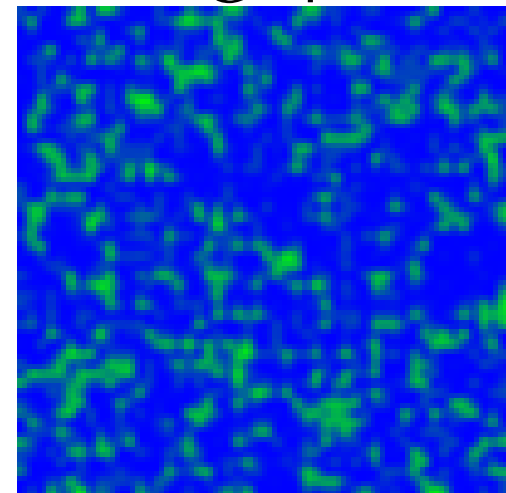
G=4



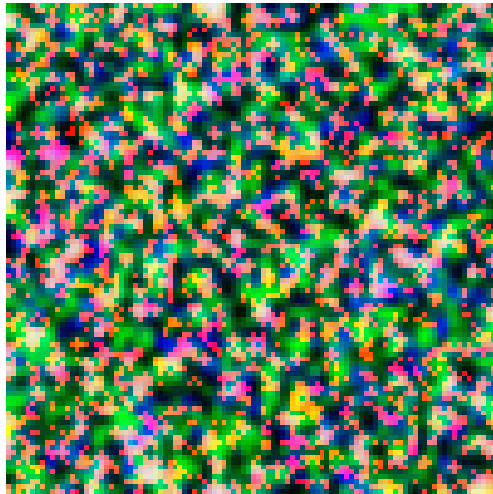
G=30



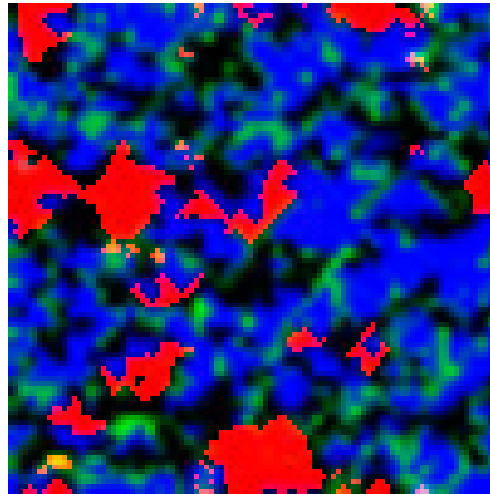
G=100



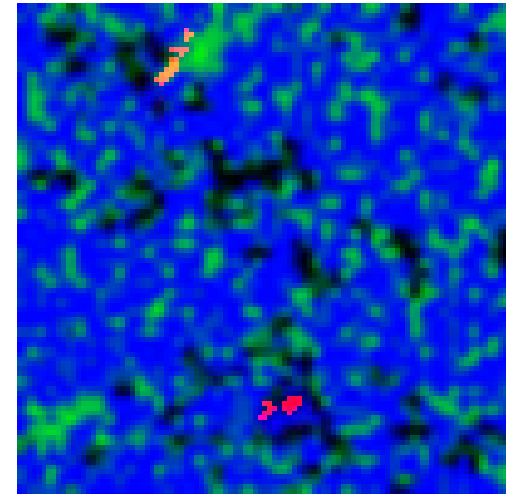
G=402



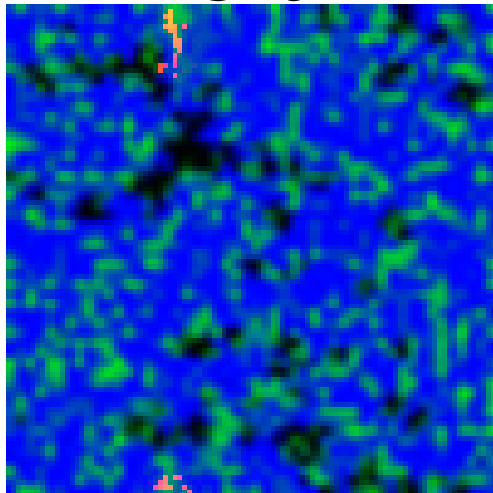
G=8



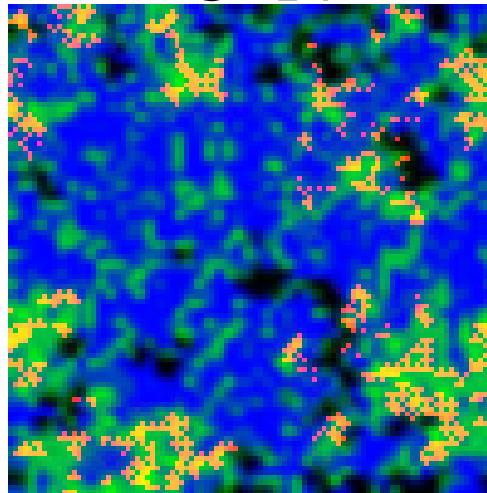
G=14



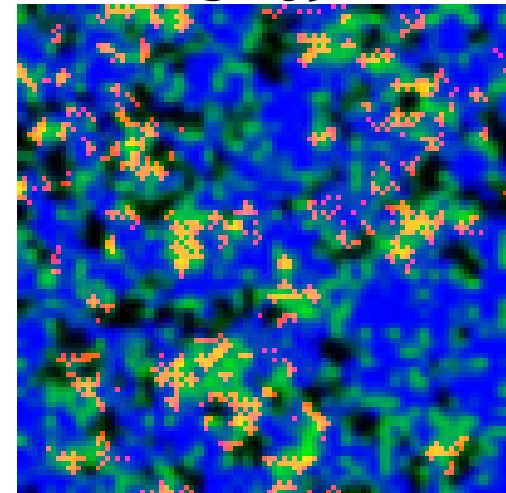
G=89



G=100



G=300

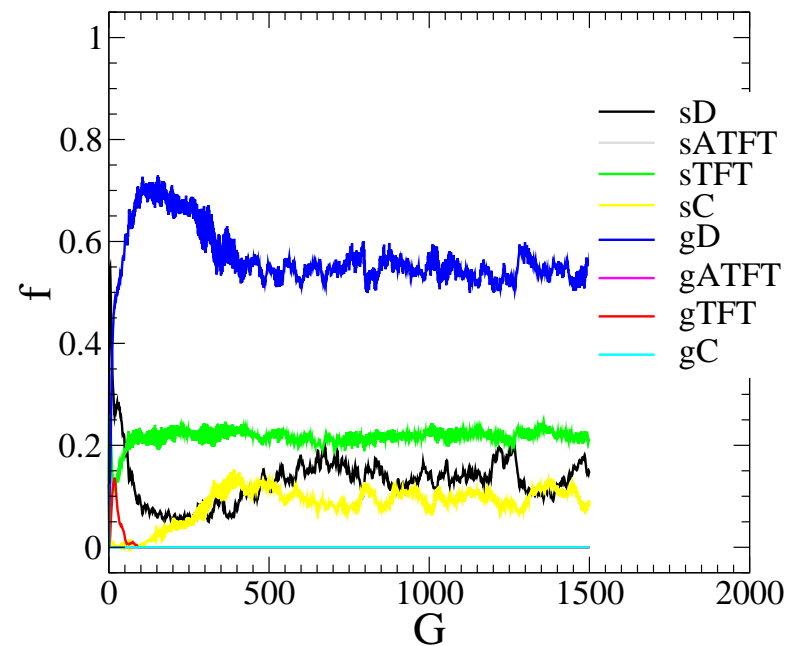
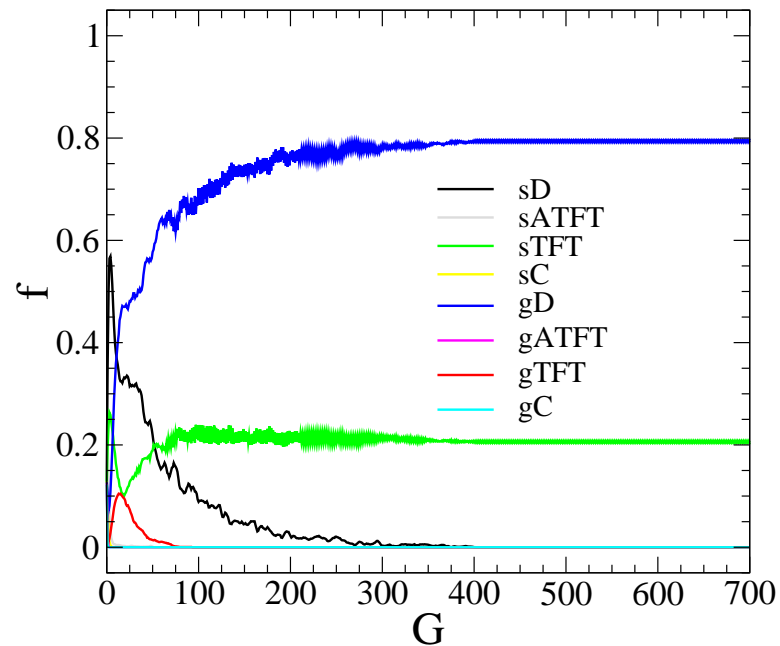


G=1500

## Results (for the “same” setup and $n_g = 2$ )

- *early stage*: steep decline of all generous strategies (except gD)
- *late stage*: gD global winner (different from gTFT)
- two different attractors for the global dynamics:
  - *stationary* coexistence of *two* strategies:  
gD, sTFT (small clusters) – i.e. sD, sC both *dissappear*
  - *non-stationary* coexistence of *four* strategies:  
gD, sTFT, sD, sC – i.e. sD, sC both *survive*  
(attractor less often reached)





- *conclusion* (valid for  $n_g = 2$ ): increase of *heterogeneity* in agents' strategies and *local* interaction  $\Rightarrow$  complex (sometimes non-stationary) IPD dynamics
- *to do*: detailed analysis of attractor size and stability

## Conclusions

- ▶ *heterogeneous* agents: play different strategies dependent on (i) past experience ( $n_m = 1$ ), (ii) local neighborhood
- ▶ spatial multi-agent system, *local* interaction: 2-person IPD  
⇒ agents:  $\mathcal{C}$  or  $\mathcal{D}$  with  $n_m = 1$  ⇒ 8 strategies  
⇒ investigate spatio-temporal evolution of heterogeneity
- ▶ outcome (for  $n_g = 2$ ) depends on initial strategy mix:
  - spatial coexistence of different strategies (large domains, small clusters, ...)
  - (g)TFT may prevail only under special conditions
  - different (stationary and non-stationary) “defective” attractors dominated by gD

➤ *global transition* into *cooperation* becomes possible, **IF**

- appropriate payoff structure  $\Rightarrow$  T, S, R, P

F.S., L. Behera, H. Mühlenbein, *Advances in Complex Systems* **5** (2002) 269-299

- repeated interaction  $\Rightarrow$  critical  $n_g > 2$

L. Behera, F.S., H. Mühlenbein, forthcoming

➤ relation to *social dynamics*: role of locality and heterogeneity  $\Rightarrow$  non-trivial results

➤ relation to *evolutionary optimization*: maximization of private (local) utility vs. overall (global) utility  $\Rightarrow$  frustration